

Assessing Delay Propagation in Airline Plans: An Update

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M.I.T.
Global Airline Industry Program

Review

- Our goal is to better understand the relationship between planned and actual operations
- How can changes in the plan improve operational performance?
- Two stages of project:
 - *Analyze* potential for delay propagation
 - *Decrease* potential for delay propagation

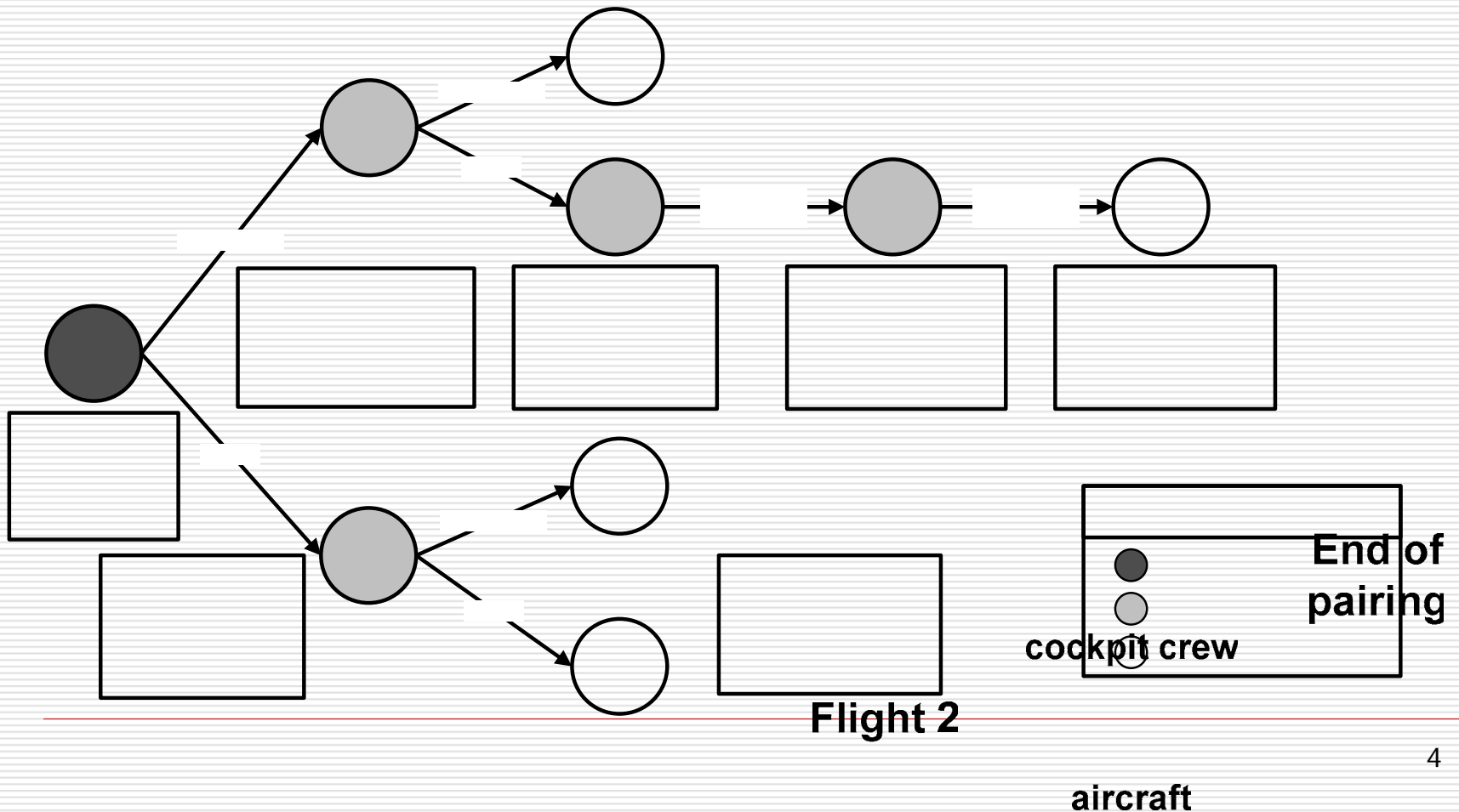
Review of Analysis

- Build *propagation trees* to evaluate how an individual *root delay* might propagate through the network
- Construct trees for each flight, each delay interval
- Summarize metrics

Propagation Tree: Example

Nodes: flights

Arcs: connections due to transfer of resources



Defining Metrics

□ Propagation magnitude

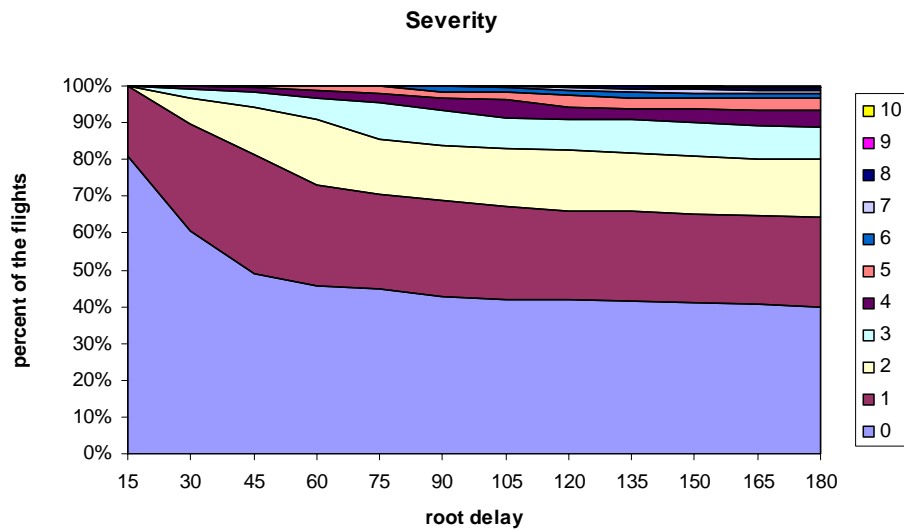
- Total minutes of delay propagated in the flight network divided by the original delay

$$\text{propagation magnitude} = \frac{\text{total propagated delays}}{\text{original delay}}$$

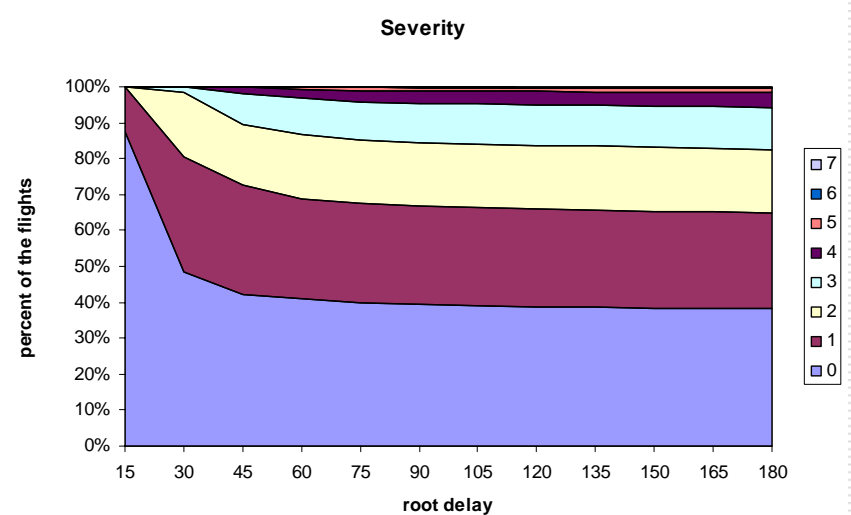
□ Propagation severity

- Total number of disrupted flights

Severity Across All Delay Lengths



Carrier 1

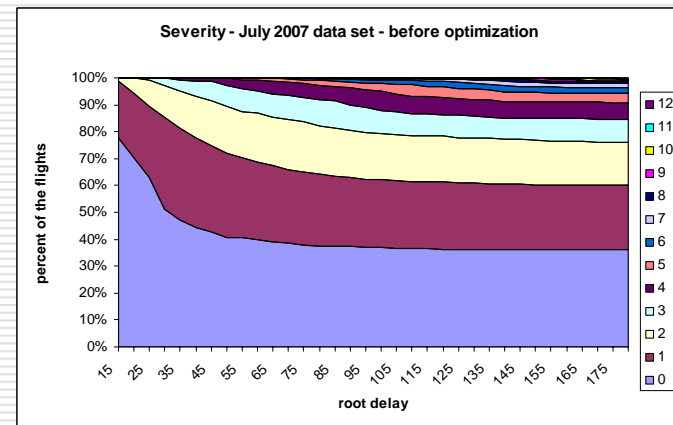
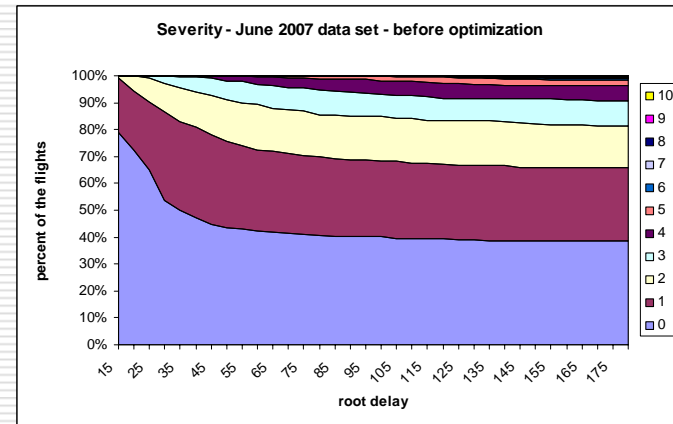
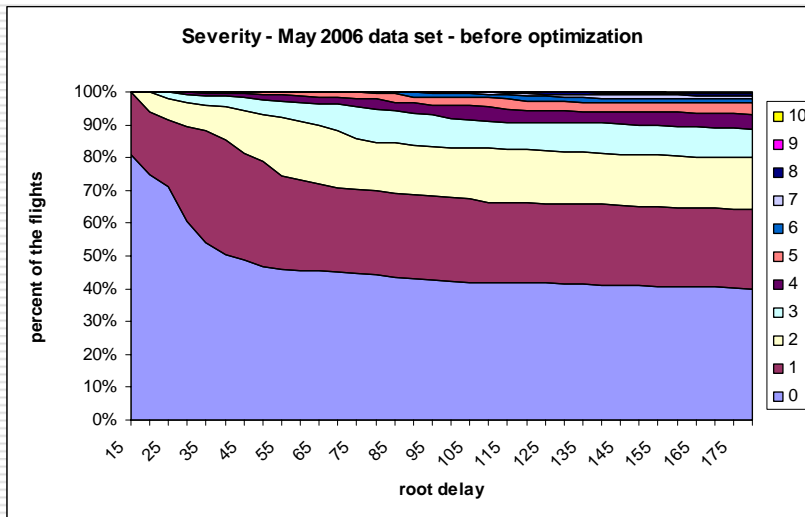


Carrier 2

What's New in Analysis

- For first carrier, evaluated two more data sets
 - Both after sizeable change in fleet composition
 - Two different dates (different demand levels, schedules, weather patterns)

Severity Across All Delay Lengths



What's Next in Analysis

- Cabin crews
- Critical passenger itineraries
- Recovery

Review of Optimization

- Can we improve robustness by changing flight times slightly, in order to better utilize the slack?
 - Don't change crew assignments, fleetings, or routing
 - Only changes are to re-allocate slack where it is most needed
- Does not capture all the opportunities to improve robustness
- A starting point that does not require explicit assignment of costs or values to delay

Linear Programming Formulation I

- Minimize the expected value of **one-layer** delay propagation while keeping the connections feasible

$$\text{Min} \quad \sum_{m \in M} \sum_{(f_1, f_2) \in F} p_{f_1}^m d_{f_1, f_2}^m$$

$$y_{f_1, f_2} = s_{f_1, f_2} + x_{f_1} + x_{f_2} \quad \forall (f_1, f_2) \in A$$

$$d_{f_1, f_2}^m \geq m - y_{f_1, f_2} \quad \forall (f_1, f_2) \in A \quad \forall m \in M$$

$$d_{f_1, f_2}^m \geq 0 \quad \forall (f_1, f_2) \in F \quad \forall m \in M$$

$$d_{f_1, f_2}^m = \max\{0, m - y_{f_1, f_2}\}$$

$$k_f^- \leq x_f \leq k_f^+ \quad \forall f \in F$$

$$y_{f_1, f_2} \geq 0 \quad \forall (f_1, f_2) \in A$$



What's New in Optimization

- ❑ First approach only looked at one layer of delay
- ❑ New approach allows delay to propagate until fully absorb
- ❑ Little change on performance (run time)
- ❑ Still a linear program
- ❑ Some difference in outcome

Linear Programming Formulation II

- Minimize the expected value of **all-layers** delay propagation while keeping the connections feasible

$$\text{Min} \quad \sum_{m \in M} \sum_{f_0 \in F} \sum_{f_i \in T_{f_0}^m} p_{f_0}^m d_{f_0, f_i}^m$$

$$y_{f_1, f_2} = s_{f_1, f_2} + x_{f_1} + x_{f_2} \quad \forall (f_1, f_2) \in A$$

$$d_{f_0, f_i}^m \geq m - y_{f_0, f_i} \quad \forall f_i \in T_{f_0}^m \text{ s.t. } r_{f_0}^m(f_i) = f_0 \quad \forall m \in M$$

$$d_{f_0, f_i}^m \geq d_{f_0, r_{f_0}^m(f_i)}^m - y_{r_{f_0}^m(f_i), f_i} \quad \forall f_i \in T_{f_0}^m \text{ s.t. } r_{f_0}^m(f_i) \neq f_0 \quad \forall m \in M$$

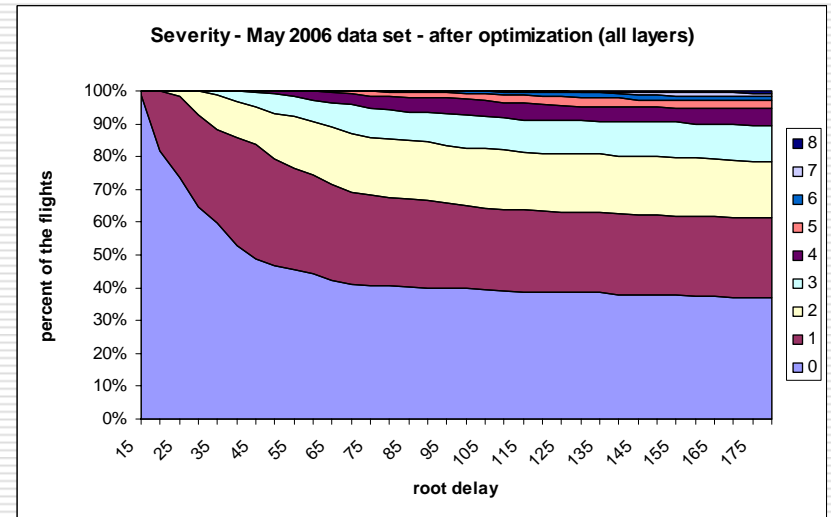
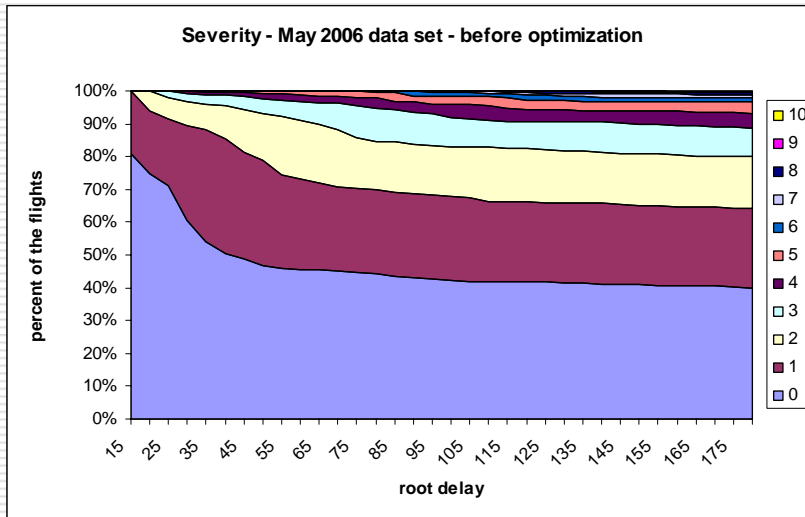
$$d_{f_0, f_i}^m \geq 0 \quad \forall f_0 \in F, f_i \in T_{f_0}^m \quad \forall m \in M$$

$$k_f^- \leq x_f \leq k_f^+ \quad \forall f \in F \quad y_{f_1, f_2} \geq 0 \quad \forall (f_1, f_2) \in A$$

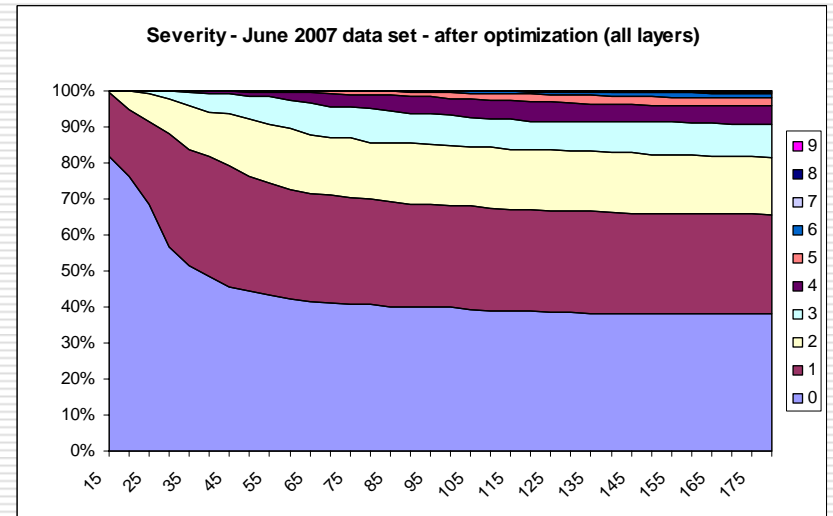
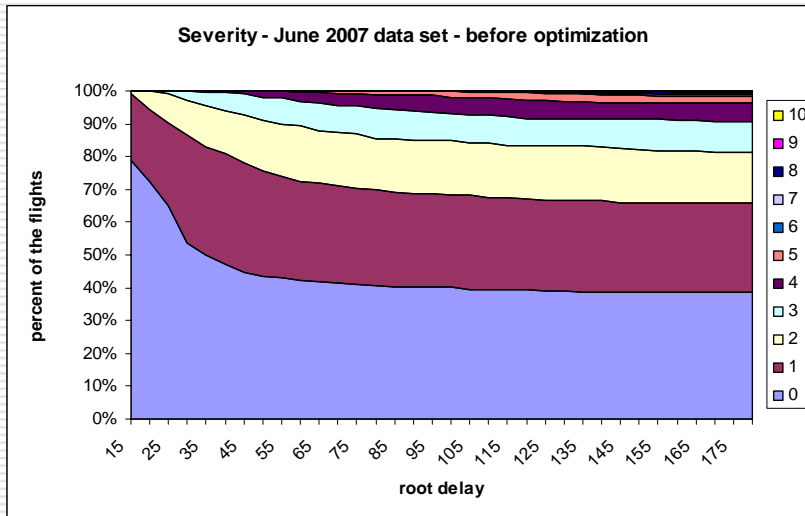
Implementation

- Implemented the model using CPLEX10.0/C++
- Used historical data in order to compute the probability of departure delays (P_f^m)
- Assumptions:
 - Equal time windows $k_f^+ = k_f^- = 15$
 - For the flights that start a duty period $k_f^+ = 15, \quad k_f^- = 0$
 - For the flights that end a duty period $k_f^+ = 0, \quad k_f^- = 15$

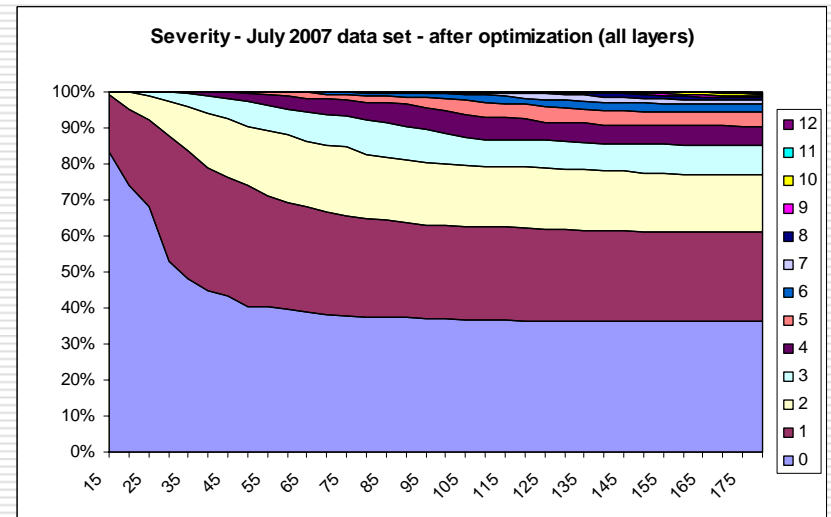
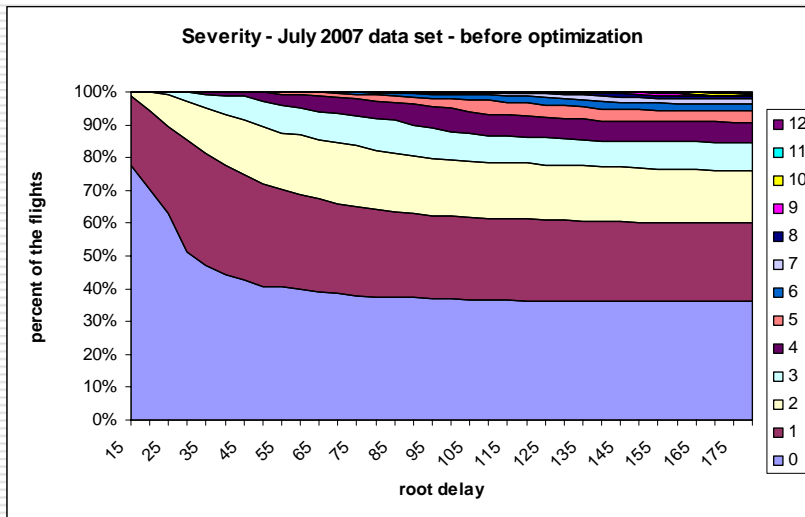
Results



Results



Results



Results, cont.

May 2006

Model I : One-layer propagation model	Model II : All-layers propagation model
obj. fun. value before opt = 789.22 obj. fun. value after opt = 519.103 reduction% = 34.2% running time = 1 sec	obj. fun. value before opt = 1187.76 obj. fun. value after opt = 768.949 reduction% = 35.3% running time = 1 sec obj. fun. based on model I = 787.989 reduction% = 33.6%

Results, cont.

June 2007

Model I : One-layer propagation model	Model II : All-layers propagation model
obj. fun. value before opt = 543.895 obj. fun. value after opt = 441.049 reduction% = 18.9% running time = 1 sec	obj. fun. value before opt = 637.878 obj. fun. value after opt = 519.523 reduction% = 18.5% running time = 2 sec obj. fun. based on model I = 526.812 reduction% = 17.4%

Results, cont.

July 2007

Model I : One-layer propagation model	Model II : All-layers propagation model
obj. fun. value before opt = 652.408 obj. fun. value after opt = 551.009 reduction% = 15.5% running time = 1 sec	obj. fun. value before opt = 758.635 obj. fun. value after opt = 636.817 reduction% = 16.05% running time = 3 sec obj. fun. based on model I = 641.107 reduction% = 15.4%

What's Next in Optimization

- Implementing a simulation to evaluate our surrogate objective function
- In the future, need to better incorporate recovery decisions

Conclusions

- ❑ Standard plea for data
- ❑ Standard plea for feedback
- ❑ Special plea for guidance about modeling recovery